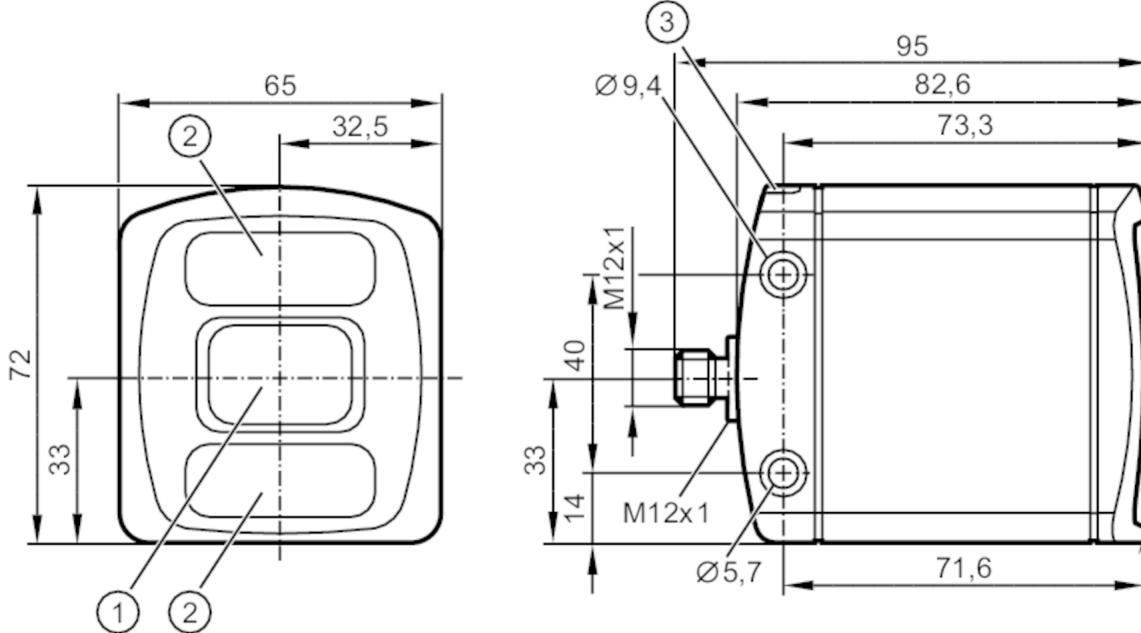


## 3D sensor

O3DIRDKG/E1/GM/S/60/ODS



- 1 lens
- 2 Illumination unit
- 3 LED 2-colour yellow/green



## Product characteristics

|                                    |  |   |
|------------------------------------|--|---|
| Type of light                      |  | infrared light  |
| Image resolution 3D [px]           |  | 176 x 132   |
| Angle of aperture 3D [°]           |  | 60 x 45; (nominal value without lens distortion correction) |
| Image repetition frequency [Hz] 3D |  | 10  |

## Application

|             |                    |
|-------------|--------------------|
| Application | obstacle detection |
|-------------|--------------------|

## Electrical data

|                               |   |
|-------------------------------|---|
| Operating voltage [V]         | 20.4...28.8 DC; (EN 61131-2)                    |
| Current consumption [mA]      | 420; (maximum mean value: < 1600 mA)            |
| Max. current consumption [mA] | 2400; (peak current pulsed)                     |
| Power consumption [W]         | 10  |
| Protection class              | III   |
| Type of light                 | infrared light                                  |
| Image sensor                  | PMD 3D ToF-Chip                                 |
| Internal lighting             | yes; (infrared: 850 nm invisible radiation LED) |
| Switch-on peak current [mA]   | 2400  |

## Detection zone

|                          |            |
|--------------------------|------------|
| Operating distance [mm]  | 200...4000 |
| Image resolution 3D [px] | 176 x 132  |

# O3DC02



## 3D sensor

O3DIRDKG/E1/GM/S/60/ODS

|                                      |                    |   |
|--------------------------------------|--------------------|---|
| Angle of aperture 3D                 | [°]                | 60 x 45; (nominal value without lens distortion correction)                                 |
| Image repetition frequency 3D        | [Hz]               | 10  |
| <b>Interfaces</b>                    |                    |   |
| Communication interface              |                    | Ethernet  |
| <b>Ethernet</b>                      |                    |   |
| Number of Ethernet interfaces        |                    | 1   |
| Transmission standard                |                    | 10Base-T; 100Base-TX  |
| Transmission rate                    |                    | 10; 100   |
| Protocol                             |                    | TCP/IP  |
| Factory settings                     |                    | IP address: 192.168.0.69<br>subnet mask: 255.255.255.0<br>gateway IP address: 192.168.0.201 |
| <b>Operating conditions</b>          |                    |   |
| Ambient temperature                  | [°C]               | -10...50  |
| Storage temperature                  | [°C]               | -40...85  |
| Protection                           |                    | IP 65; IP 67  |
| Max. immunity to extraneous light    | [klx]              | 8   |
| <b>Tests / approvals</b>             |                    |   |
| EMC                                  | DIN EN 61000-6-4   | radiation of interference / industrial environments   |
|                                      | DIN EN 61000-6-2   | immunity / industrial environments  |
| Shock resistance                     | DIN EN 60068-2-27  | 50 g / (11 ms) not repetitive   |
|                                      | DIN EN 60068-2-27  | 40 g / (6 ms) repetitive  |
| Vibration resistance                 | DIN EN 60068-2-6   | 2 g / (10...150 Hz)   |
|                                      | DIN EN 60068-2-64  | 2.3 g RMS / (10...500 Hz)   |
| Photobiological safety               |                    | exempt group; (DIN EN 62471)  |
| Electrical protection                | DIN EN 61010-2-201 | electrical supply only via PELV circuits  |
| <b>Mechanical data</b>               |                    |   |
| Weight                               | [g]                | 770   |
| Dimensions                           | [mm]               | 72 x 65 x 82.6  |
| Materials                            |                    | housing: diecast aluminium; front pane: Gorilla Glass; function display: PA                 |
| <b>Displays / operating elements</b> |                    |   |
| Display                              | function           | 2 x LED, green Ethernet operation   |
| <b>Аксесуари</b>                     |                    |   |
| Items supplied                       |                    | spring washers  |
| <b>Remarks</b>                       |                    |   |
| Pack quantity                        |                    | 1 pcs.  |

# O3DC02

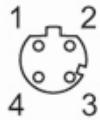


## 3D sensor

O3DIRDKG/E1/GM/S/60/ODS

### Electrical connection - Ethernet

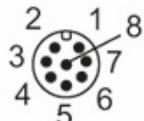
Connector: 1 x M12; coding: D



|   |      |
|---|------|
| 1 | TD + |
| 2 | RD + |
| 3 | TD - |
| 4 | RD - |

### Electrical connection - Process connection

Connector: 1 x M12; coding: A



|   |     |
|---|-----|
| 1 | U+  |
| 2 | nc  |
| 3 | GND |
| 4 | nc  |
| 5 | nc  |
| 6 | nc  |
| 7 | nc  |
| 8 | nc  |

### Other data

#### Field of view size

| measuring range / distance [m] | Length [m] | Breite [m] |
|--------------------------------|------------|------------|
| 0.50                           | 0.4        | 0.56       |
| 1.00                           | 0.8        | 1.13       |
| 2.00                           | 1.6        | 2.26       |
| 3.00                           | 2.4        | 3.39       |
| 4.00                           | 3.2        | 4.52       |

# O3DC02



## 3D sensor

O3DIRDKG/E1/GM/S/60/ODS

### input/output parameters

|                   |   |
|-------------------|---|
| input parameters  | Information on own movement of the automated guided vehicle (AGV)   |
|                   | NTP-server for time synchronisation                                 |
| output parameters | distance  |
|                   | occupancy grid ± 5m in x and y direction of the vehicle coordinates |
|                   | occupation state of the warning zones                               |

### setting parameters

| Parameter   | Setting range   |
|---|---|
| warning zones   | three independent warning zones for obstacle detection    |
| extrinsic calibration   | calibration of the camera position in vehicle coordinates |
| each warning zone is defined via a convex 2D polygon with max.<br>6 corners and a global height |   |

### obstacle detection

| example obstacles   | latency [ms]                                      |                        |
|---|---|------------------------|
|   | typical value                                     | typical value          |
|   | object already in the field of view of the camera | initial detection [ms] |
| forklift fork (lateral, 25cm above ground)                  | 200   | 700                    |
| box or container (surface facing the sensor<br>> 200x200mm) | 200   | 700                    |
| bicycle (lateral & front)                                   | 200   | 700                    |

The indications on the detection time of the obstacles are based  
on the following assumptions

speed of the automated guided vehicle < 1.7 m/s

medium reflectivity of the objects

minimum height of the objects 15cm above ground