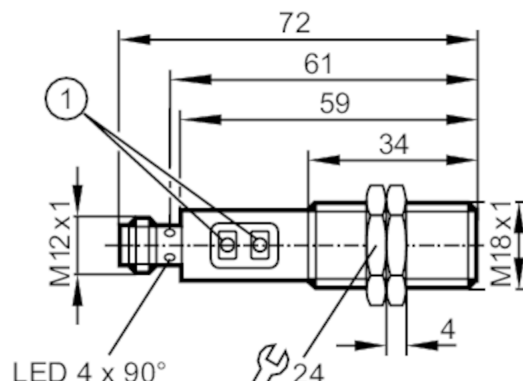




Diffuse reflection sensor with background suppression

OGH-CPKG/US100



1 programming buttons



Product characteristics

Type of light	red light
Housing	threaded type

Application

Special feature	Background suppression
Function principle	Diffuse reflection sensor

Electrical data

Operating voltage	[V]	10...36 DC; ("supply class 2" to cULus)
Current consumption	[mA]	25
Protection class		II
Reverse polarity protection		yes
Type of light		red light
Wave length	[nm]	624

Outputs

Electrical design		PNP
Output function		complementary
Max. voltage drop switching output DC	[V]	2.5
Permanent current rating of switching output DC	[mA]	150; (200 (...60 °C))
Switching frequency DC	[Hz]	1000
Short-circuit protection		yes
Type of short-circuit protection		pulsed
Overload protection		yes

Detection zone

Range	[mm]	15...300; (white paper 200 x 200 mm 90% remission)
Range on white object (90 % remission)	[mm]	15...300
Range on grey object (18 % remission)	[mm]	15...290



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Range on black object (6 % remission) [mm]	15...190
Range adjustable	yes
Max. light spot diameter [mm]	25
Light spot dimensions refer to	at maximum range
Background suppression available	yes

Operating conditions

Ambient temperature [°C]	-25...80
Protection	IP 67

Tests / approvals

EMC	EN 60947-5-2	
MTTF [years]	575	
UL approval	Ta	-25...80 °C
	Enclosure type	Type 1
	power supply	Class 2
	File number UL	E174191

Mechanical data

Weight [g]	61.2
Housing	threaded type
Dimensions [mm]	M18 x 1 / L = 72
Thread designation	M18 x 1
Materials	stainless steel (316L/1.4404); PA; LCP; EPDM; TPU
Lens material	PMMA

Displays / operating elements

Display	switching status	1 x LED, yellow
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Accessories

Items supplied	lock nuts: 2
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Remarks

Pack quantity	1 pcs.
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Electrical connection

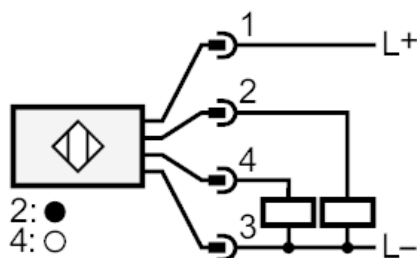
Connector: 1 x M12; coding: A



Diffuse reflection sensor with background suppression

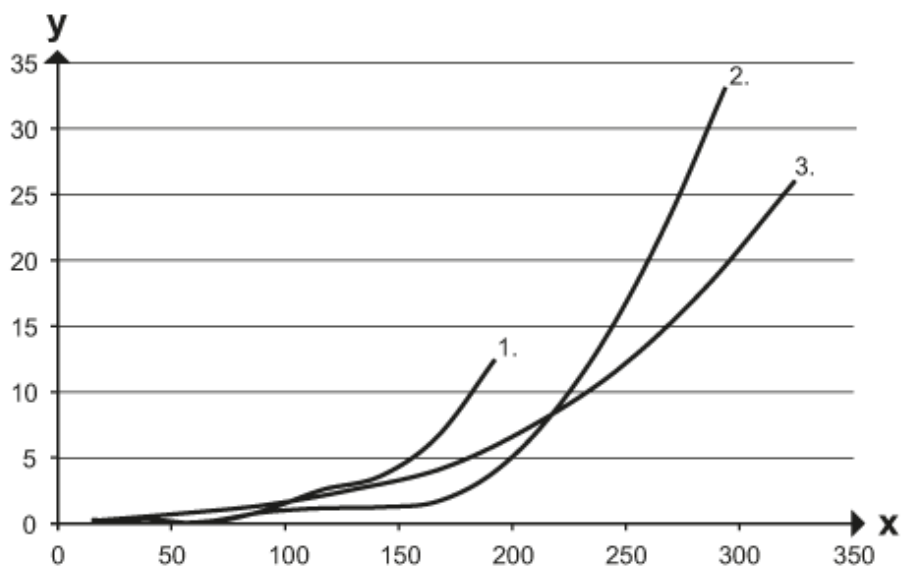
OGH-CPKG/US100

Connection



Diagrams and graphs

accuracy graph



x: distance sensor/object [mm]

y: min. distance object/background [mm]

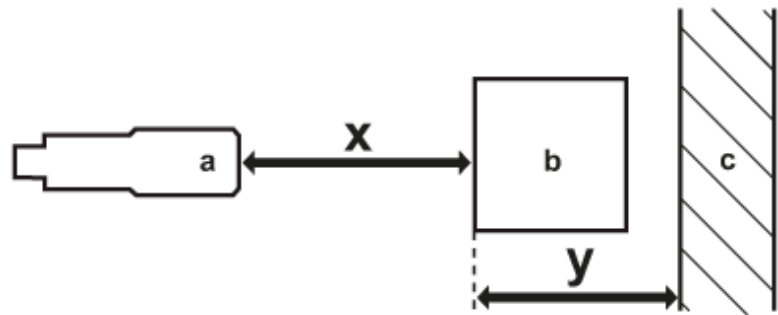
1 = object black (6 % remission) , background white (90 % remission)

2 = object grey (18 % remission) , background white (90 % remission)

3 = object white (90 % remission) , background white (90 % remission)

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a: sensor

b: object

c: background

x: distance sensor/object [mm]

y: min. distance object/background [mm]