Operating instructions
Electronic level sensor
LR2750
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1 Preliminary note
1.1 Symbols used

► Instructions
> Reaction, result
[...] Designation of keys, buttons or indications
→ Cross-reference

⚠ Important note
Non-compliance may result in malfunction or interference.

ℹ Information
Supplementary note.

2 Safety instructions

• Read this document before setting up the product and keep it during the entire service life.

• The product must be suitable for the corresponding applications and environmental conditions without any restrictions.

• Only use the product for its intended purpose (→ Functions and features).

• Only use the product for permissible media (→ Technical data sheet).

• If the operating instructions or the technical data are not adhered to, personal injury and/or damage to property may occur.

• The manufacturer assumes no liability or warranty for any consequences caused by tampering with the product or incorrect use by the operator.

• Installation, electrical connection, set-up, operation and maintenance of the product must be carried out by qualified personnel authorised by the machine operator.

• Protect units and cables against damage.
3 Items supplied

- 1 level sensor LR2750
- 1 operating instructions

In addition, the following is necessary for installation and operation:

- 1 rod (→ Accessories)

▶ In the event of incomplete or damaged items supplied please contact ifm electronic.

⚠▶ Only use accessories from ifm electronic.

Accessories: www.ifm.com

The optimum function is not ensured when using components from other manufacturers.

4 Getting started

For the most frequent applications the quick set-up described below is possible. The quick set-up does not replace observance of the other chapters.

▶ Install the unit correctly:
  Installation distances (→ 7.1), electrical connection (→ 8).

▶ Set rod length (→ 11.2).

> The unit is ready for operation.

⚠ Without changes = factory settings active (→ 15).

Change of the factory settings (→ 11).

▶ Optional: Carry out tank adjustment (→ 11.2.2).

▶ If necessary, make more settings for adaptation to the application (→ 11.3) and (→ 11.4).

▶ Check whether the unit operates correctly.
5 Functions and features

The unit continuously detects the level in tanks.

5.1 Applications

- Food and hygienic areas.
- Applications with increased requirements for protection rating and resistance (→ Technical data sheet).

The unit complies with the standard EN 61000-6-4 and is a class A product. The unit may cause radio interference in domestic areas. If interference occurs, the user must take appropriate actions.

The microwave energy radiated by the unit is much below that of mobile phones. According to the current state of science the operation of the unit can be classified to be harmless to human health if it is used as intended.

5.1.1 Restriction of the application area

Incorrect measurements may be caused by the following media:

- Highly absorbing surfaces (e.g. foam).
- Intensely bubbling surfaces.
- Media which are very inhomogeneous, separate from each other thus forming separation layers (e.g. oil layer on water).

► Check the function by performing an application test.
► Installation in a steady area (→ 7.1).
> In case of signal loss, the unit displays [SEnS] and switches the outputs to a defined state (→ 12.8).

- The unit is not suitable for bulk materials (e.g. plastic granulates) and media with a very low dielectric constant, e.g. oils.
- The unit is not suitable for applications where the rod is subjected to permanent and high mechanical stress (e.g. fast moving viscous media or fast flowing media).
- Use preferably in metal tanks. When used in plastic tanks, deterioration caused by electromagnetic interference may occur (noise immunity to EN61000-6-2). Refer to: (→ 7.4.2).
6 Function

6.1 Measuring principle

The unit operates on the principle of guided wave radar. It measures the level using electromagnetic pulses in the nanosecond range.

The pulses are transmitted by the sensor head and guided along the rod (fig. 6-1). When they hit the medium to be detected they are reflected and guided back to the sensor (fig. 6-2). The time between transmitting and receiving the pulse directly relates to the travelled distance (D) and the current level. The reference for distance measurement is the lower edge of the process connection.

6.2 Outputs

The unit generates output signals according to the parameter setting. 2 outputs are available. They can be set separately.

<table>
<thead>
<tr>
<th>OUT1</th>
<th>switching signal for level limit / IO-Link (→ 6.3.7)</th>
</tr>
</thead>
</table>
| OUT2       | • analogue signal proportional to the level 4...20 mA / 20...4 mA  
            | or                                                   |
|            | • switching signal for level limit                   |

6.3 Other features of the unit

- Hygienic approvals / conformities (→ Technical data sheet)
- For CIP / SIP applications (→ Technical data sheet)
- Special operating mode for media with increased foam build-up (→ 11.6.2)
• Tank adjustment enables suppression of undesired interference
  (e.g. caused by structures in the tank or when mounted in a connection piece
  (→ 11.2.2))
• Display of the level and the switching status via display / LEDs
• IO-Link function (→ 6.3.7)

6.3.1 Display functions
The unit displays the current level, either in mm, inch or in percent of the scaled
measuring range. Factory setting: mm.
The display unit is defined by programming (→ 11.3).
In the operating mode, the user can switch between the length display (mm, inch)
and percentage (→ 12.6).
The set unit of measurement and the switching status of the outputs are indicated
by LEDs (→ 9).

6.3.2 Analogue function
The unit provides an analogue signal proportional to level. The analogue output
(OUT2) can be set ((→ 11.4.8) and the following illustrations).
• [ou2] defines the output function of the analogue output:
  current output rising [ou2] = [I] or
  current output falling [ou2] = [InEG] (→ 11.4.8).
• The analogue start point [ASP2] defines at which measured value the analogue
  start value* can be provided (→ 11.4.9).
• The analogue end point [AEP2] defines at which measured value the analogue
  end value* is provided (→ 11.4.9).

*) The analogue start value is 4 mA with [ou2] = [I] or 20 mA with
[ou2] = [InEG].
  The analogue end value is 20 mA with [ou2] = [I] or 4 mA with [ou2] = [InEG].
Minimum distance between [ASP2] and [AEP2] = 20 % of the active zone.
Curve of the analogue signal (factory setting):  

Curve of the analogue signal (measuring range scaled):  

L: level  
A: active zone = L - (I1 + I2)  
I1: inactive zone 1  
I2: inactive zone 2 (→ Technical data sheet)  
ASP2: analogue start point  
AEP2: analogue end point  

Additional information about the analogue output: (→ 12.8)  
Note the tolerances and accuracy limits during the evaluation of the analogue signal (→ Technical data sheet).
6.3.3 Switching functions

Via switching output OUT1 (factory setting) or additionally via OUT2 (can be set) the unit signals that a set limit level has been reached or that the level is below the limit. The following switching functions can be selected:

- Hysteresis function / normally open (fig. 6-3): \([\text{oux}] = [\text{Hno}]\)
- Hysteresis function / normally closed (fig. 6-3): \([\text{oux}] = [\text{Hnc}]\)

⚠️ First the set point (SPx) is set, then the reset point (rPx) with the requested difference.

- Window function / normally open (fig. 6-4): \([\text{oux}] = [\text{Fno}]\)
- Window function / normally closed (fig. 6-4): \([\text{oux}] = [\text{Fnc}]\)

⚠️ The width of the window can be set by means of the difference between \([\text{FHx}]\) and \([\text{FLx}]\). \([\text{FHx}]\) = upper value, \([\text{FLx}]\) = lower value.

**Fig. 6-3**

<table>
<thead>
<tr>
<th>L</th>
<th>HY</th>
<th>Hno</th>
<th>Hnc</th>
</tr>
</thead>
<tbody>
<tr>
<td>SP</td>
<td>rP</td>
<td>t</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
</tbody>
</table>

**Fig. 6-4**

<table>
<thead>
<tr>
<th>L</th>
<th>FE</th>
<th>FH</th>
<th>FL</th>
</tr>
</thead>
<tbody>
<tr>
<td>t</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
</tbody>
</table>

- The adjustable limits (e.g. SP / rP) always refer to the lower edge of the rod.
- For the switching output a switch-on and switch-off delay of max. 60 s can be set (e.g. for especially long pump cycles) (→ 11.4.4).
6.3.4 Damping function
With unsteady level (e.g. turbulence, wave movements) display and output response can be damped. During damping the determined level values are "smoothed" by means of a mean filter; the result is a steady curve. Damping can be set by means of the parameter [dAP] (∴ 11.4.10). [dAP] indicates in seconds after what time 63% of the final value are reached in the event of a sudden jump. After 5 x [dAP] almost 100% have been reached.

6.3.5 Rods for different tank heights
The unit can be installed in tanks of different sizes. Rods in different lengths are available. To adapt to the tank height, each rod can be shortened. The minimum rod length is 150 mm, the maximum rod length 2000 mm.

6.3.6 Defined state in case of a fault
• In case of a fault a state can be defined for each output.
• If a fault is detected or if the signal quality is below a minimum value, the outputs pass into a defined state. Applies to the analogue output according to Namur recommendation (NE43). For this case the response of the outputs can be set via the parameters [FOU1], [FOU2] (∴ 11.4.9).
• Temporary loss of signal caused e.g. by turbulence or foam build-up can be suppressed by a delay time (parameter [dFo] → 11.4.11). During the delay time the last measured value is frozen. If the measured signal is received again in sufficient strength within the delay time, the unit continues to work in normal operation. If, however, it is not received again in sufficient strength within the delay time, the outputs pass into the defined state.

In case of heavy foam build-up and turbulence, note the examples of how to create a steady area (∴ 7.1.1)
6.3.7 IO-Link

This unit has an IO-Link communication interface which requires an IO-Link-capable module (IO-Link master) for operation.

The IO-Link interface enables direct access to the process and diagnostic data and provides the possibility to set the parameters of the unit during operation. In addition communication is possible via a point-to-point connection with a USB adapter cable.

The IODDs necessary for the configuration of the unit, detailed information about process data structure, diagnostic information, parameter addresses and the necessary information about the required IO-Link hardware and software can be found at www.ifm.com.

6.3.8 Simulation functions

Various levels and errors can be simulated for set-up, maintenance or interference reduction. The duration of the simulation can be selected (1 min...1 h). The simulation can be started manually and runs until it is stopped manually or the set time elapses. During the simulation the outputs respond according to the simulated process values (→ 11.7) to (→ 11.7.3).

7 Installation

7.1 Installation location / environment

- Vertical installation from the top is preferred.
  - Observe the notes on tank adjustment (→ 7.1.7).
- Installation preferably in closed, metal tanks or bypass pipes.
  - For installation in open tanks (→ 7.4.1)
  - For installation in plastic tanks (→ 7.4.2).

7.1.1 Minimum distances and connection piece diameter

- Select a connection piece height that is smaller than the connection piece diameter.
7.1.2 Installation in pipes

- Installation only if hygienic requirements are met.
- Only install the unit in metal pipes.
- The internal pipe diameter d must at least have the following value:

<table>
<thead>
<tr>
<th></th>
<th>With adjustment (→ 7.1.7)</th>
<th>Without adjustment</th>
</tr>
</thead>
<tbody>
<tr>
<td>d</td>
<td>Ø 30 mm</td>
<td>Ø 100 mm with [MEdl] = [HIGH]</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Ø 250 mm with [MEdl] = [MId] (→ 11.6.2)</td>
</tr>
</tbody>
</table>

Depending on the operating conditions (flow) and mechanical design of the pipe the use of centring pieces is recommended (→ Accessories).
7.1.3 Applications with viscous and fast flowing media
For applications with viscous or flowing media and/or agitators in which the rod is exposed to lateral load:

► Rod must not be in contact with tank wall/structures.
► Increase lateral minimum distances according to the rod length and the lateral deflection to be expected.
► If possible, fix the rod at the lower end so that it is electrically conductive. This can be done by means of a sleeve or similar devices (fig. 7-3).
► Check the correct function (in particular with empty tank).

7.1.4 Fill openings
Do not install the unit in the immediate vicinity of a fill opening (fig. 7-4).
7.1.5 Highly polluted medium
If the medium is highly polluted, there is the risk that a bridge forms between the rod and the tank wall or structures in the tank.
► Increase minimum distances depending on the pollution intensity.

7.1.6 Heavy foam build-up and turbulence

⚠️ Heavy foam build-up and turbulence may lead to incorrect measurements.
To avoid this
► install the sensor in a steady area by meeting the hygienic requirements.
Examples how to create a steady area:
• Installation in metal bypass or metal still pipe (fig. 7-5).
• Separation of the installation location by metal sheets / perforated sheets (without fig.).

![Fig. 7-5](image)

- d: minimum diameter (→ 7.1.2)

⚠️ The upper access to the steady area (A, B) must be above the max. level. The lower access (C, D) or the area with perforated sheet must be below the min. level. This ensures that neither foam nor turbulence impact the sensor zone. When perforated sheets or similar are used, soiling (e.g. solids in the medium) can also be avoided.
With increased foam build-up the setting $[MEdI] = [MId]$ $(\rightarrow 11.6.2)$ is recommended

7.1.7 Notes on tank adjustment

Tank adjustment reduces the effect of interference and ensures a higher excess gain in difficult application conditions.

Carry out the tank adjustment only when the unit is installed.

For the tank adjustment it is necessary to enter an "adjustment distance" first. Within this distance, starting from the process connection, interfering reflections are compensated.

► Select an adjustment distance (a) so that the connection piece (S) and structures in the tank (B) are completely detected.

► Observe safety distance ($b \geq 250$ mm) to the level or the rod end.

![Diagram showing tank adjustment with labels a, b, S, and B]

- a: adjustment distance (min: 10 mm; max: $L - 250$ mm)
- b: safety distance to the level or rod end: $b \geq 250$ mm
- S: connection piece
- B: structures in the tank

For rod lengths $L < 260$ mm no tank adjustment is possible. The parameter $[tREF]$ is then not available. In this case:

► Adhere to all indicated installation distances $(\rightarrow 7.1)$. 
No tank adjustment is necessary if all installation distances (→ 7.1) are adhered to. The unit is then ready for operation without adjustment.
► In case of doubt carry out a tank adjustment (recommended!).

Carry out a tank adjustment with empty tank, if possible, to detect any possible sources of interference. In this case:
► Select the max. adjustment distance (L - 250 mm).

Only if data storage is required in an IO-Link application:
The tank adjustment is not saved via IO-Link! After a replacement it must be carried out again.
More information about data storage: (→ 16.2).

7.2 Installation of the rod
The rod is not supplied (→ 3 Items supplied).

7.2.1 Installation of the rod
► Do not damage the surfaces of the process connection and rod.
   Use suitable tools with plastic surfaces.

Fixing of the rod:
► Remove the protective cover / protective devices from the unit and the rod.
► Slip the supplied O-ring onto the rod connection of the unit or check its position.
► Screw the rod to the unit and tighten it.
  Recommended tightening torque: 6.5 Nm.
► Check the O-ring for correct position.
  Replace if damaged.

In case of high mechanical stress (strong vibration, moving viscous media) it may be necessary to secure the screw connection, e.g. by a screw retaining compound.
► Substances such as screw retaining compounds may migrate into the medium.
  Make sure that they are harmless.
7.3 Rod length
7.3.1 Shorten rod

The rod can be shortened to adapt to different tank heights.

- Ensure that the rod length is not below the minimum permissible rod length ($L_{\text{min}}$) of 150 mm. The unit does not support rod lengths below 150 mm.
- With rod lengths $< 260$ mm no tank adjustment is possible (→ 7.1.7 Notes on tank adjustment).

Proceed as follows:

▶ Screw the rod to the unit.
▶ Mark the desired length ($L$) on the rod. The reference point is the lower edge of the process connection.
▶ Remove the rod from the unit. Make sure that the O-ring between the rod attachment piece and the rod does not get lost.
▶ Shorten the rod at the mark.
▶ Remove all burrs and sharp edges. For hygienic requirements: Restore the required surface quality. If necessary, repolish.

▶ Check the position of the O-ring / insert the O-ring again.
▶ Screw the rod to the unit again and tighten it. Recommended tightening torque: 6.5 Nm.

In case of high mechanical stress (strong vibration, moving viscous media) it may be necessary to secure the screw connection, e.g. by a screw retaining compound.

- Substances such as screw retaining compounds may migrate into the medium.
  ▶ Make sure that they are harmless.
7.3.2 Determine rod length

► Precisely measure the rod length L. The reference point is the lower edge of the process connection (fig. above).

► Note the value. It is needed for setting the device parameters (→ 11.2.1).

7.4 Installation of the unit in the tank

⚠ Before installing and removing the unit: Make sure that no pressure is applied to the system and that there is no medium in the tank that could leak. Also always take into account the potential dangers related to extreme machine and medium temperatures.

The unit can be fixed to different process connections (→ Accessories). Options are as follows:

<table>
<thead>
<tr>
<th>1</th>
<th>Fitting by means of a mounting or welding adapter with a sealing ring (hygienic)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>The adapter is supplied with an EPDM O-ring. Further sealing rings (e.g. FKM O-ring) are available as accessories. Concerning installation → Installation instructions of the adapter.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>2</th>
<th>Installation on G1 flange (non hygienic)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>The sealing ring on the sensor is used as process seal. The upper sealing area on the process connection must be flush with the tapped hole and have a surface characteristic of min. Rz 6.3.</td>
</tr>
</tbody>
</table>

The sensor housing cannot be aligned. With non alignable process connections (e.g. welding adapters) take into account the final position of the sensor housing (readability of the display, cable entry). Observe marks at adapters. If needed, screw in the unit and mark the requested alignment.

If no other installation instructions apply, proceed as follows:

► Lightly grease the thread of the sensor using a lubricating paste which is suitable and approved for the application.

► Insert the unit into the process connection.

► Tighten it using a spanner. Tightening torque: 35 Nm
7.4.1 Installation in open tanks

► For installation in open tanks, use a metal fixture to install the unit. It serves as a launching plate (R); minimum size: 150 x 150 mm for a square fixture, 150 mm diameter for a circular fixture (→ 12.1).

► If possible, mount the unit in the middle of the fixture. Adhere to the specified installation distances according to (→ 7.1), if necessary, carry out a tank adjustment.

D1: min. 150 mm
R: launching plate

7.4.2 Installation in plastic tanks

D1: min. 150 mm
R: launching plate

To enable sufficient transfer of the measured signal, note in case of installation in plastic tanks or metal tanks with plastic lid:
► The plastic lid must be provided with a drill hole with a minimum diameter of 150 mm.

► For installation of the unit, a metal flange plate (= launching plate, R) must be used which sufficiently covers the drill hole (→ 12.1).

► Ensure a minimum distance (= 80 mm) between the rod and the tank wall. Adhere to the installation instructions (→ 7.1.2) to (→ 7.1.6), if necessary carry out a tank adjustment.

When installed in plastic tanks, there may be deterioration caused by electromagnetic interference from other devices. To avoid this:

   • Apply a metal foil to the outside of the tank
   • Apply a shielding screen between the level sensor and other electronic units
   • Additional installation in a metal pipe only if hygienic requirements are met. Permissible diameters: (→ 7.1.2)

7.4.3 Note on the use according to EHEDG

The unit has an approval according to EHEDG. It is only valid in conjunction with adapters with EHEDG approval. → Accessories: www.ifm.com.

► Make sure that the sensor is integrated into the system according to EHEDG.

7.4.4 Notes on the use according to 3-A

► Make sure that the sensor is integrated into the system according to 3-A.

► Use only 3-A certified adapters marked with the 3-A symbol → Accessories: www.ifm.com.

The process connection must be provided with a self-draining leakage port. When adapters with 3-A certification are used, this is guaranteed.

► It is recommended to choose an installation position where the rod and the process connection can be cleaned with a spray ball.

_for use according to 3-A, special regulations apply for cleaning and maintenance (→ 14.1).

Not suitable for systems which must meet the criteria of paragraph E1.2 / 63-03 of the 3-A standard 63-03.
8 Electrical connection

The unit must be connected by a qualified electrician.
The national and international regulations for the installation of electrical equipment must be adhered to.

Voltage supply according to EN 50178, SELV, PELV.

For marine applications (if approval available for the device), additional surge protection is required.

► Disconnect power.
► Connect the unit as follows:

<table>
<thead>
<tr>
<th>Core colours</th>
<th>2</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td>BK</td>
<td>black</td>
<td></td>
</tr>
<tr>
<td>BN</td>
<td>brown</td>
<td></td>
</tr>
<tr>
<td>BU</td>
<td>blue</td>
<td></td>
</tr>
<tr>
<td>WH</td>
<td>white</td>
<td></td>
</tr>
</tbody>
</table>

OUT1: switching output / IO-Link
OUT2: analogue output / switching output
Colours to DIN EN 60947-5-2

Example circuits

2 x positive switching

1 x positive switching / 1 x analogue

1 x negative switching / 1 x analogue
When operating voltage is applied to the unit for the first time, the rod length must be entered first (\(\rightarrow\) 11.2.1). Only then is the unit ready for operation.

9 Operating and display elements

<table>
<thead>
<tr>
<th>1 to 8: Indicator LEDs</th>
</tr>
</thead>
<tbody>
<tr>
<td>LEDs 1 - 3</td>
</tr>
<tr>
<td>LEDs 4 - 6</td>
</tr>
<tr>
<td>LED 7</td>
</tr>
<tr>
<td>LED 8</td>
</tr>
</tbody>
</table>

9: [Enter] button
- Open the user menu, edit and confirm the parameter values.

10 to 11: Arrow keys up [▲] and down [▼]
- Selection of the parameters
- Setting of the parameter values (continuously by holding pressed; incrementally by pressing once).

12: Alphanumeric display, 4 digits
- Display of the current level.
- Display of the parameters and parameter values.
Menu items highlighted in grey, e.g. [SP2], are only active when assigned parameters have been selected (→ 10.2.1).

I: Main menu (→ 10.2.1)
II: Level EF (→ 10.2.2)
Menu items highlighted in grey, e.g. [dS2], are only active when assigned parameters have been selected (→ 10.2.3).

III: Level CFG (→ 10.2.3)
IV: Level ENV (→ 10.2.4)
V: Level SIM (→ 10.2.5)
# 10.2 Explanation of the menu

## 10.2.1 Main menu

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>tREF</td>
<td>Carry out tank adjustment. Menu item only visible if [LEnG] ≥ 260 mm.</td>
</tr>
<tr>
<td>SP1 / rP1</td>
<td>Set point 1 / reset point 1 at which OUT1 switches. Menu point only visible if hysteresis function is selected ([ou1] = [H..])</td>
</tr>
<tr>
<td>FH1 / FL1</td>
<td>Upper / lower limit for the acceptable range within which OUT1 switches. Menu item only visible if window function is selected ([ou1] = [F..])</td>
</tr>
<tr>
<td>ASP2</td>
<td>Analogue start point 2: measured value at which the analogue start value is provided. The analogue start value is set with parameter [ou2]. Menu item only visible if analogue output ([ou2] = [I] or [InEG]) is selected</td>
</tr>
<tr>
<td>AEP2</td>
<td>Analogue end point 2: measured value at which the analogue end value is provided. The analogue end value is set with parameter [ou2]. Menu item only visible if analogue output ([ou2] = [I] or [InEG]) is selected</td>
</tr>
<tr>
<td>SP2 / rP2</td>
<td>Set point 2 / reset point 2 at which OUT2 switches. Menu item only visible if hysteresis function is selected ([ou2] = [H..])</td>
</tr>
<tr>
<td>FH2 / FL2</td>
<td>Upper / lower limit for the acceptable range within which OUT2 switches. Menu item only visible if window function is selected ([ou2] = [F..])</td>
</tr>
<tr>
<td>EF</td>
<td>Extended functions / opening of menu level 2</td>
</tr>
</tbody>
</table>

## 10.2.2 Level EF (extended functions)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>rES</td>
<td>Restore the factory setting (all parameters incl. tank adjustment)</td>
</tr>
<tr>
<td>CFG</td>
<td>Open the submenu CFG (configuration)</td>
</tr>
<tr>
<td>ENV</td>
<td>Open the submenu ENV (environment parameter)</td>
</tr>
<tr>
<td>SIM</td>
<td>Open the submenu SIM (simulation)</td>
</tr>
</tbody>
</table>
### 10.2.3 Level CFG (configuration)

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ou1</td>
<td>Output configuration for OUT1: switching signal for level limit value. Hysteresis or window function, normally closed or normally open</td>
</tr>
</tbody>
</table>
| ou2          | Output configuration for OUT2:  
|              | • analogue signal for current level, 4…20 mA or 20…4 mA  
|              | or  
|              | • switching signal for level limit. Hysteresis or window function, normally closed or normally open |
| dS1          | Switch-on delay for OUT1 |
| dr1          | Switch-off delay for OUT1 |
| dS2*         | Switch-on delay for OUT2 |
| dr2*         | Switch-off delay for OUT2 |
| uni          | Selection of the unit of measurement on the sensor display; mm or inch |
| P-n          | Output polarity of the switching outputs; positive or negative switching |
| FOU1         | Response of OUT1 in case of a fault |
| FOU2         | Response of OUT2 in case of a fault |
| SELd         | Selection of display options |
| dAP          | Damping of the measured signal (mean filter) |
| dFo          | Delay time for the outputs to pass into the state defined with FOUx; only effective in case of a fault |

* Menu item only visible if hysteresis or window function ([ou2] = [H..] or [F..]) is selected.

### 10.2.4 Level ENV (environment)

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LEnG</td>
<td>Input of the rod length</td>
</tr>
<tr>
<td>MEdI</td>
<td>Medium selection</td>
</tr>
</tbody>
</table>

### 10.2.5 Level SIM (simulation)

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>S.LvL</td>
<td>Simulation of a level / an error state</td>
</tr>
<tr>
<td>S.Tim</td>
<td>Simulation duration 1...60 min</td>
</tr>
<tr>
<td>S.On</td>
<td>Simulation start/stop</td>
</tr>
</tbody>
</table>
11 Parameter setting
During parameter setting the unit remains in the operating mode internally. It continues to monitor with the existing parameters until the parameter setting has been completed.

11.1 Parameter setting in general
3 steps must be taken for each parameter setting:

1. Select parameter
   ▶ Press [Enter] to get to the menu.
   ▶ Press [▲] or [▼] until the required parameter is displayed.

2. Set parameter value
   ▶ Press [Enter] to edit the selected parameter.
   ▶ Press [▲] or [▼] for at least 1 s.
     After 1 s: setting value is changed: incrementally by pressing the button once or continuously by keeping the button pressed.

   Numerical values are incremented continuously with [▲] or decremented with [▼].

3. Acknowledge parameter value
   ▶ Press [Enter].
     The parameter is displayed again.
     The new setting value is saved.

Set other parameters
▶ Press [▲] or [▼] until the required parameter is displayed.

Finish parameter setting
▶ Press [▲] or [▼] several times until the current measured value is displayed or wait for 30 s.
▶ The unit returns to the process value display.
[C.Loc] or [S.Loc] as operation indication see (→ 12.7)

- Change from menu level 1 to menu level 2:
  
  ► Press [Enter] to get to the menu.
  
  ► Press [▲] or [▼] until [EF] is displayed.
  
  ► Press [Enter].
  
  > The first parameter of the submenu is displayed (here: [rES]).

- Timeout:

  If no button is pressed for 30 s during parameter setting, the unit returns to the process value display with unchanged values.

- Lock / unlock

  The unit can be locked electronically to prevent unintentional settings. Factory setting: unlocked

  ► Make sure that the unit is in the normal operating mode.
  
  ► Press [▲] + [▼] simultaneously for 10 s.
  
  > [Loc] is displayed.

  During operation: [Loc] is briefly displayed if you try to change parameter values.

  For unlocking:
  
  ► Press [▲] + [▼] simultaneously for 10 s.
  
  > [uLoc] is displayed.
11.2 Basic settings (set-up)

On delivery of the unit, you must first enter the rod length. The complete user menu then opens.

11.2.1 Enter rod length

► Apply operating voltage.
> The initial display is shown.
► Press [Enter] and select [LEnG].
► Press [Enter] again.
> [nonE] is displayed.
► Press [▲] or [▼] for at least 1 s.
> After 1 s the unit automatically displays the detected rod length (preset function*).
► Correct the rod length, if necessary, with [▲] or [▼]. Incrementally by pressing the button once or continuously by keeping the button pressed. Enter the rod length in mm.
► Press [Enter].

* Automatic rod length detection is only possible with empty tank and sufficiently large launching plate.

• Manual determination of the rod length: (→ 7.3.2)

Then the unit goes to the operating mode.

If necessary (e.g. in case of installation in a connection piece) carry out a tank adjustment and make further settings to adapt to the application.

11.2.2 Carry out tank adjustment

Menu item only visible if [LEnG] ≥ 260 mm.
► Observe notes (→ 7.1.7).
► Select [tREF].
► Press [Enter].
> [nonE] or the value saved from the last tank adjustment (distance value) is displayed.
► Press [▲] or [▼] for at least 1 s.
> The distance value is displayed (default value: 10 mm.).
► Correct the value, if necessary, with [▲] or [▼]. Incrementally by pressing the button once or continuously by keeping the button pressed.
► Press [Enter].
> [donE] is displayed.
► Press [Enter] again.
> The unit reboots and then returns to the operating mode.
### 11.3 Configure display (optional)

- Select [uni] and set the unit of measurement: [mm], [inch].
- Select [SELD] and set type of indication:
  - [L] = The level is indicated in mm or inch.
  - [%] = The level is indicated in percent. The displayed level in % depends on the parameters:
    - ASP2 = set value corresponds to 0 %
    - AEP2 = set value corresponds to 100 %
  - [OFF] = The display is switched off in the operating mode. When one of the buttons is pressed, the current measured value is displayed for 30 s. The indicator LEDs remain active even if the display is deactivated.

### 11.4 Set output signals

#### 11.4.1 Set output function for OUT1

- Select [ou1] and set the switching function:
  - [Hno] = hysteresis function / normally open
  - [Hnc] = hysteresis function / normally closed
  - [Fno] = window function / normally open
  - [Fnc] = window function / normally closed

Note: If the switching output is used as an overflow prevention, the setting [ou1] = [Hnc] (normally closed function) is recommended. The principle of normally closed operation ensures that wire break or cable break is also detected.

#### 11.4.2 Set switching limits (hysteresis function)

- Make sure that the function [Hno] or [Hnc] is set for [oux].
- Select [SPx] and set the value at which the output is set.
- Select [rPx] and set the value at which the output is reset.

[rPx] is always smaller than [SPx]. The unit only accepts values which are lower than the value for [SPx]. If [SPx] is shifted, [rPx] also shifts provided that the lower end of the setting range is not reached.
11.4.3 Set switching limits (window function)

- Make sure that for [oux] the function [Fno] or [Fnc] is set.
- Select [FHx] and set the upper limit of the acceptable range.
- Select [FLx] and set the lower limit of the acceptable range.

[FLx] is always lower than [FHx]. The unit only accepts values which are lower than the value for [FHx]. If [FHx] is shifted, [FLx] also shifts provided that the lower end of the setting range is not reached.

11.4.4 Set switch-on delay for switching outputs

- Select [dSx] and set the value between 0.0 and 60 s.

The switch-on delay reacts according to VDMA*).

11.4.5 Set switch-off delay for switching outputs

- Select [drx] and set the value between 0.0 and 60 s.

The switch-off delay reacts according to VDMA*).

*) According to VDMA the switch-on delay always has an effect on SP, the switch-off delay always on rP irrespective of whether the normally open or normally closed function is used.

11.4.6 Set output function for OUT2

- Select [ou2] and set the switching function:

[I] = current output 4...20 mA
[InEG] = current output 20...4 mA
[Hno] = hysteresis function / normally open
[Hnc] = hysteresis function / normally closed
[Fno] = window function / normally open
[Fnc] = window function / normally closed

Note: If the output is used as an overflow prevention, the setting [ou2] = [Hnc] (NC function) is recommended. The principle of normally closed operation ensures that wire break or cable break is also detected.
11.4.7 Scale analogue signal

► Select [ASP2] and set the analogue start point.
► Select [AEP2] and set the analogue end point.
Setting these parameters via IO-Link is only possible if parameter [ou2] = [I] or [InEG].
More information: (→ 6.3.2)

11.4.8 Set output logic for switching outputs

► Select [P-n] and set [PnP] or [nPn].

11.4.9 Set response of the outputs in case of a fault

► Select [FOU1] / [FOU2] and set the value:
    Analogue output switches to a value > 21 mA in case of a fault.
  - [OFF] = Switching output switches OFF in case of a fault.
    Analogue output switches to a value < 3.6 mA in case of a fault.
Examples of faults: defective hardware, signal quality too low.
Overflow is not considered to be a fault.

11.4.10 Set damping for measured signal

► Select [dAP] and set damping in seconds; setting range 0.0...60.0 s (→ 6.3.4).

11.4.11 Set delay time in case of a fault

► Select [dFo] and set a value between 0.0 and 10.0 s.
[dFo] only effective in case of a fault! Mind the dynamics of your application.
In case of fast level changes it is recommended to adapt the value step by step (→ 6.3.6).

11.5 Reset all parameters to factory setting

► Select [rES]
► Press [Enter] until [rES] is displayed right aligned.
► Press and hold [▲] or [▼] until [----] is displayed.
► Briefly press [Enter].
> The unit reboots and the factory settings are restored.
Note: On delivery the unit is not operational. First, the basic settings must be entered (→ 10.2).
11.6 Change basic settings
Required after changes to the rod or application.

11.6.1 Re-enter rod length

► Select [LEnG].
► Enter the rod length L. Note the set unit [uni].
► Press [Enter].

Note: After changing the rod length, the values for the switching limits must also be reviewed / re-entered.

More information: (→ 11.2.1).

11.6.2 Set to another medium

► Select [MEdI] and set:

[HIGH] = For water and water-based media.
Operating mode is optimised for suppression of deposits on the rod.

[MId] = For water-based media and media with a medium dielectric constant value, e.g. water-in-oil emulsions.
Operating mode optimised for the detection of media with increased foam build-up.

► Press [Enter].

Note: In case of doubt carry out an application test to ensure the setting best suited for the medium.

11.7 Simulation

11.7.1 Set simulation value

► Select [S.LvL]
► Set the process value to be simulated:

[Numerical value] = level in mm / inch (depending on the basic setting)
[FULL] = full state
[SEnS] = weak measured signal
[Err] = electronic fault found
[EPTY] = empty state

► Press [Enter].
11.7.2 Set simulation duration

- Select [STim]
- Set time span for simulation.
- Press [Enter].

Setting range: 1, 2, 3, 4, 5, 10, 15, 20, 30, 45, 60 min.
Factory setting: 3 min

11.7.3 Switch simulation on / off

- Select [S.On] and set:
  [OFF] =  simulation off
  [On] =  simulation on
- Press [Enter] to start the simulation.

The simulation is active until [Enter] is pressed again or the time set via [STim] elapses. During the simulation [SIM] is displayed every 3 s.
After the simulation the unit goes again to the parameter [S.On] and internally the unit goes again to the operating mode (and the process value transmission).
After another 30 s the display goes again to the process value display.

If the simulation is started via IO-Link, it can only be finished via IO-Link.
During the attempt to finish the simulation via the buttons, C.Loc is displayed.

12 Operation

12.1 Operation with single rod

This unit is only intended for operation with a single rod. A coaxial rod is not available for this unit.
Operation with a single rod is suited for the detection of aqueous media, in particular of heavily soiled aqueous media.

For a correct function the unit needs a sufficiently large metal launching surface / launching plate. It is necessary for transferring the microwave pulse to the tank with optimum transmission power.
For installation in closed metal tanks / metal bypass pipes, the tank lid / upper pipe section serves as a launching surface. For installation in open metal tanks, plastic tanks or metal tanks with plastic lids a sufficiently large fixing plate, a metal plate or similar must be used (→ 7.4.1) (→ 7.4.2).
12.2 Operation with a bypass or still pipe
In certain applications it is recommended to use a bypass or still pipe, e.g. in case of heavy foam build-up (→ 7.1.6).
Minimum internal pipe diameter: (→ 7.1.2)
General installation instructions: (→ 7.1)

12.3 Function check
After power on the unit is in the operating mode. It carries out its measurement and evaluation functions and generates output signals according to the set parameters.
► Check whether the unit operates correctly.

12.4 Operation indication

<table>
<thead>
<tr>
<th>Indication</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>---- continuous</td>
<td>Initialisation phase after power on</td>
</tr>
<tr>
<td>----</td>
<td>On delivery the unit is not operational. Basic settings required (→ 11.2).</td>
</tr>
<tr>
<td>[----]</td>
<td>Level below the active zone</td>
</tr>
<tr>
<td>Numerical value + LED 1</td>
<td>Current level in mm</td>
</tr>
<tr>
<td>Numerical value + LED 2</td>
<td>Current level in inches</td>
</tr>
<tr>
<td>Numerical value + LED 3</td>
<td>Current level in % of the scaled measuring range</td>
</tr>
<tr>
<td>LED 7 / LED 8</td>
<td>Switching status OUT2 / OUT1</td>
</tr>
<tr>
<td>[FULL] + numerical value alternately</td>
<td>Level has reached or exceeded the maximum measuring range (= overflow warning).</td>
</tr>
<tr>
<td>[SIM] + xxx</td>
<td>Simulation active. XXX = state to be simulated (→ 11.7)</td>
</tr>
<tr>
<td>[S.On]</td>
<td>Simulation stopped (→ 11.7)</td>
</tr>
<tr>
<td>[Loc]</td>
<td>Unit locked via buttons; parameter setting is not possible. For unlocking press the two setting buttons for 10 s.</td>
</tr>
<tr>
<td>[uLoc]</td>
<td>Unit is unlocked / parameter setting is possible again.</td>
</tr>
<tr>
<td>[C.Loc]</td>
<td>The unit is temporarily locked. Parameter setting via IO-Link active.</td>
</tr>
<tr>
<td>[S.Loc]</td>
<td>Unit permanently locked via IO-Link. Unlocking is only possible via IO-Link.</td>
</tr>
</tbody>
</table>
12.5 Read set parameters
► Briefly press [Enter] to open the menu
► [▲] or [▼] scrolls through the parameters.
► Briefly press [Enter] to indicate the corresponding parameter value for about 30 s. Then the unit returns to the process value display.

12.6 Change between length display and percentage
Length display: mm or inch (→ 11.3)
► Briefly press [▲] or [▼] in the operating mode.
> The selected unit is displayed for 30 s, the corresponding LED is on. With each push of the button the display type is changed.

12.7 Error indications

<table>
<thead>
<tr>
<th>Possible cause</th>
<th>Recommended measures</th>
</tr>
</thead>
<tbody>
<tr>
<td>[Err] Fault in the electronics.</td>
<td>Replace the unit.</td>
</tr>
<tr>
<td>[nPrb] Rod detached from the unit; possibly incorrect setting of the rod length.</td>
<td>Check whether the rod is still attached to the unit. Check the parameter [LEnG].</td>
</tr>
<tr>
<td>Measurement disturbed by heavy foam build-up or turbulence.</td>
<td>• Install the unit in a still pipe or bypass (→ 7.1).&lt;br&gt;• Set or increment [dFo] (→ 11.4.11).</td>
</tr>
<tr>
<td>Measurement disturbed by separation layers (e.g. oil layer on water).</td>
<td>Remove the oil layer by suction, stir the medium, verify the composition.</td>
</tr>
<tr>
<td>[SEnS] Rod or process connection soiled.</td>
<td>Clean the rod and the process connection.</td>
</tr>
<tr>
<td>Installation conditions not adhered to.</td>
<td>Observe the notes in &quot;Installation&quot; (→ 7). Carry out or repeat a tank adjustment (→ 11.2.2).</td>
</tr>
<tr>
<td>Rod length or sensitivity (setting to the medium) incorrect.</td>
<td>Correct settings, then carry out tank adjustment, if necessary (→ 7.1.7).</td>
</tr>
<tr>
<td>[SCx] + LED 7&lt;br&gt;[SCx] + LED 8</td>
<td>Flashing: short circuit in switching output OUT1 or OUT2. Remove the short circuit.</td>
</tr>
<tr>
<td>[SC] + LED 7&lt;br&gt; + LED 8</td>
<td>Flashing: short circuit in both switching outputs Remove the short circuit.</td>
</tr>
</tbody>
</table>
Possible cause | Recommended measures
---|---
[PArA] Faulty data set | Restore factory settings (→ 11.5).

### 12.8 Output response in different operating states

<table>
<thead>
<tr>
<th></th>
<th>OUT1</th>
<th>OUT2*</th>
</tr>
</thead>
<tbody>
<tr>
<td>Initialisation</td>
<td>OFF</td>
<td>OFF</td>
</tr>
<tr>
<td>Normal operation</td>
<td>According to the level and [ou1] setting</td>
<td>According to the level 4...20 mA</td>
</tr>
<tr>
<td>Fault</td>
<td>OFF with [FOU1] = OFF; ON with [FOU1] = On</td>
<td>&lt; 3.6 mA with [FOU2] = OFF; &gt; 21 mA with [FOU2] = On</td>
</tr>
</tbody>
</table>

* If the analogue function [ou2] = [I] has been selected.
  If the switching function has been selected: see column OUT1

<table>
<thead>
<tr>
<th>Additions to the analogue output</th>
<th></th>
</tr>
</thead>
</table>
| Full signal | With [ou2] = [I]: 20...20.5 mA  
With [ou2] = [InEG]: 4...3.8 mA |
| Empty signal | With [ou2] = [I]: 4...3.8 mA  
With [ou2] = [InEG]: 20...20.5 mA |
### Technical data


### Setting ranges

<table>
<thead>
<tr>
<th>[LEnG]</th>
<th>mm</th>
<th>inch</th>
</tr>
</thead>
<tbody>
<tr>
<td>Setting range</td>
<td>150...2000</td>
<td>6.0...78.8</td>
</tr>
<tr>
<td>Step increment</td>
<td>5</td>
<td>0.2</td>
</tr>
</tbody>
</table>

The setting ranges for the switching limits ([SPx], [rPx], [FHx], [FLx]) depend on the rod length (L). In general the following applies:

<table>
<thead>
<tr>
<th></th>
<th>mm</th>
<th>inch</th>
</tr>
</thead>
<tbody>
<tr>
<td>[SPx] / [FHx]</td>
<td>15</td>
<td>L - 30</td>
</tr>
<tr>
<td>[rPx] / [FLx]</td>
<td>10</td>
<td>L - 35</td>
</tr>
<tr>
<td>Step increment</td>
<td>1</td>
<td>0.05</td>
</tr>
</tbody>
</table>

- [rPx] / [FLx] is always smaller than [SPx] / [FHx]. If [SPx] / [FHx] is shifted, [rPx] / [FLx] also shifts provided that the lower end of the setting range is not reached. Always set [SPx] / [FHx] first, then [rPx] / [FLx].

The setting ranges for analogue start point [ASP2] and analogue end point [AEP2] depend on the rod length (L). In general the following applies:

<table>
<thead>
<tr>
<th></th>
<th>mm</th>
<th>inch</th>
</tr>
</thead>
<tbody>
<tr>
<td>[ASP2]</td>
<td>0</td>
<td>---</td>
</tr>
<tr>
<td>[AEP2]</td>
<td>---</td>
<td>L - 30</td>
</tr>
<tr>
<td>Step increment</td>
<td>1</td>
<td>0.05</td>
</tr>
</tbody>
</table>

- Minimum distance between [ASP2] and [AEP2] = 20 % of the active zone.
14 Maintenance / Transport

► Keep the process connection free of deposits and foreign bodies.
► In case of heavy soiling: Clean process connection and rod.

⚠️ For cleaning purposes the unit can be removed from the adapter and the rod can be screwed off the unit.

⚠️ Before installing and removing the unit:
Make sure that no pressure is applied to the system and that there is no medium in the tank that could leak.
Also always note the potential dangers related to extreme machine and medium temperatures.

► Only use suitable tools with plastic surface for wetted surfaces.
► Ensure that the connection point unit - rod or unit - adapter is not soiled or damaged. Check sealing ring(s) for damage.

If sealing rings are damaged:
► Replace damaged parts (www.ifm.com).

⚠️ When the medium is changed, it may also be necessary to adapt the settings of the unit (→ 11.6.2 Set to another medium).

⚠️ Only if data storage is required in an IO-Link application:
The tank adjustment is not saved via IO-Link. After a replacement it must be carried out again (→ 11.2.2).
More information about data storage: (→ 16.2).

► It is not possible to repair the unit.
► After use dispose of the unit in an environmentally friendly way in accordance with the applicable national regulations.
► In case of returns ensure that the unit is free from soiling, especially dangerous and toxic substances.
14.1 Cleaning and maintenance when used in 3-A applications
Submit the unit at regular intervals to COP cleaning. To do so the unit must be removed from the adapter and the rod must be screwed off the unit.

⚠️ Before installing and removing the unit:
Make sure that no pressure is applied to the system and that there is no medium in the tank that could leak.
Also always take into account the potential dangers related to extreme machine and medium temperatures.

► Remove the rod from the unit.
► Remove O-ring from the sensor
► Remove O-ring from the groove and clean it
► Before reassembly check O-ring and groove

14.2 Transport
► For transport only use appropriate packaging to avoid damage of the unit.
When the unit is installed in a machine and transported with the machine:
► Protect the machine and the unit against shock and vibration. Protect the rod against deflections and vibrations. If necessary, fix at several points to prevent movement of unstable areas.
## 15 Factory setting

<table>
<thead>
<tr>
<th>Factory setting</th>
<th>User setting</th>
</tr>
</thead>
<tbody>
<tr>
<td>tREF</td>
<td>nonE</td>
</tr>
<tr>
<td>SP1</td>
<td>50% VMR*</td>
</tr>
<tr>
<td>rP1</td>
<td>5 mm below SP1</td>
</tr>
<tr>
<td>ASP2</td>
<td>0 % VMR*</td>
</tr>
<tr>
<td>AEP2</td>
<td>100 % VMR*</td>
</tr>
<tr>
<td>dS1</td>
<td>0.0</td>
</tr>
<tr>
<td>dr1</td>
<td>0.0</td>
</tr>
<tr>
<td>ou1</td>
<td>Hno</td>
</tr>
<tr>
<td>ou2</td>
<td>l</td>
</tr>
<tr>
<td>uni</td>
<td>mm</td>
</tr>
<tr>
<td>P-n</td>
<td>PnP</td>
</tr>
<tr>
<td>FOU1</td>
<td>OFF</td>
</tr>
<tr>
<td>FOU2</td>
<td>OFF</td>
</tr>
<tr>
<td>SELd</td>
<td>L</td>
</tr>
<tr>
<td>dAP</td>
<td>0.0</td>
</tr>
<tr>
<td>dFo</td>
<td>3.0</td>
</tr>
<tr>
<td>LEnG</td>
<td>nonE</td>
</tr>
<tr>
<td>MEdl</td>
<td>MID</td>
</tr>
<tr>
<td>S.LVL</td>
<td>50 % LEnG</td>
</tr>
<tr>
<td>S.Tim</td>
<td>3</td>
</tr>
<tr>
<td>S.On</td>
<td>OFF</td>
</tr>
</tbody>
</table>

* VMR = final value of the measuring range = LEnG value minus 30 (in millimetres). When the LEnG value is entered, the unit calculates the basic setting.
16 Notes on parameter setting via IO-Link

On delivery the unit is not operational.

During set-up, valid basic settings have to be sent to the device once even if the default settings correspond to the connected device. Make sure that the basic settings are entered correctly according to the attached rod and the medium to be detected.

16.1 Recommended procedure to avoid errors during parameter setting

➤ Enter rod length (parameter [LEnG]). Example: [LEnG] = [1000] mm.
➤ Scale analogue output (parameters [ASP2] and [AEP2]; [AEP2] must at least be 20 % greater than [ASP2]!). Example: [AEP2] = [970] mm.
➤ Alternatively: Set parameter [ou2] to [H..] or [F..].
➤ Select the medium (parameter [MEdI]). Example: [MEdI] = [MId].
  • [HIGH] = For water and water-based media. Operating mode is optimised for suppression of deposits on the rod.
  • [MId] = For water-based media and media with a mean dielectric constant value. Operating mode is optimised for media with increased foam build-up.
➤ Transfer the sensor data to the unit.
➤ Carry out tank adjustment depending on the installation (parameter [tREF] or button "TEACH_TANK_REF".

If the adjustment distance (parameter [RefDist]) is to be adapted, this individual parameter has to be sent to the sensor first. Then the tank adjustment can be carried out. Select the adjustment distance according to, for example, the height of connection pieces or the position of structures in the tank. Within the adjustment distance, starting from the process connection, interfering reflections are compensated. Example: [RefDist] = [50] mm.
➤ Now all other settings can be carried out.

⚠️ Only if data storage is required in an IO-Link application:
The tank adjustment is not saved via IO-Link. After a unit has failed it must be carried out again. Only when the tank adjustment has been carried out successfully does the unit revert to the cyclical process data transmission.
After a factory reset (button "Restore Factory Settings"), the device reboots and the factory settings are restored.

16.2 Unit locking / data storage

The IO-Link master saves all parameters of the connected sensor (except tank adjustment) if configured in the master (data storage). When a sensor is replaced by a sensor of the same type, the parameters of the old sensor are automatically written to the new sensor if configured in the master and if the sensor allows this. For safety reasons the parameter download can be refused by the sensor.

Factory setting: [Open]

<table>
<thead>
<tr>
<th>Data storage</th>
<th>- [Open] = unit allows parameter download from the master</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>- [Locked] = unit refuses parameter download from the master</td>
</tr>
</tbody>
</table>

More information at www.ifm.com